MarlinTPC Installation Updated slides from the MarlinTPC installation session of the April 2009 MarlinTPC tutorial

Martin Killenberg

Uni Bonn / CERN



Last update: 8. 7. 2010

同 ト イヨト イヨト ヨヨ わくべ



Goal of this session:1

- Installing Marlin (incl. all dependencies) using ilcinstall
- Installing MarlinTPC manually from the subversion repository
 - Easier to track changes and to update
 - You can make you own processors, e. g. for analysis

We will NOT install

- Software from/for ILCSoft that is not needed for Marlin (Geant, Mokka)
- Additional processor packages for Marlin (especially those who need the CERNLIB, like MarlinReco or MarlinUtil)

¹This document is especially interesting when you are not running on Scientific Linux. For SL4/5 there are 32 bit binary packages available at http://ilcsoft.desv.de/portal/binary releases/

Dependencies of Marlin

You need the **development** packages of:



In addition you need CVS, svn, Python and a C++ compiler.

²Optional

³Takes VERY long to compile

Martin Killenberg (Uni Bonn / CERN)

MarlinTPC Installation



ilcinstall

ilcinstall is a Python script that simplifies and automates the installation of ILCSoft.



- Starting point for all ILCSoft packages: ilcsoft.desy.de
- Always download the latest tag from the svn repository. Links on the ilcsoft web page might be outdated.
- Configure which packages to install (the main work)
- Run ilcinstall

Note:

ILCSoft is continuously evolving. You should keep track of the versions you are installing. Proposed directory structure:

- ilcinstall versions have to be downloaded manually
- version directories in ilcsoft are generated by ilcinstall

The ilcinstall Config File

A few variables you need:

- ilcsoft = ILCSoft("/usr/local/ilcsoft/v01-09") Specifies the target path of the installation
- ilcsoft.downloadType = "svn"

Recommended when installing HEAD versions so one can access the revision information to know exactly which version is installed

• ilcsoft.envcmake["BUILD_32BIT_COMPATIBLE"]="OFF" When compiling on a 64 bit machine you should compile in native 64 bit.⁴

The three main commands:

- ilcsoft.install(Marlin("v00-12")) Install a package with the given version.
- ilcsoft.use(RODT("/usr/local/root/v5.26.00b")) Use a package already installed on you system.
 - Either use absolute path
 - or give version number (package is linked manually in ILCSoft path)
- ilcsoft.link(ROOT("/usr/local/root/v5.26.00b"))

Create symlink to the absolute path in the ILCSoft target directory. I never had any use for this.





- Base your config on the latest release in the ilcsoft releases directory. This ensures that the package versions work together.
- Never use packages from DESY afs when not running Scientific Linux!
- Only use packages from DESY afs when you have a fast, permanent network connection to DESY.
- If your distribution brings a package: Use it.
- Only install what you really need. Especially packages depending on CERNLIB are known to make trouble during installation.
- If running on 64 bit Linux install in native 64 bit mode. Only use 32 bit compatibility if required (e. g. for CERNLIB). In this case you need 32 bit compatibility packages for **all** dependencies.

▲ ∃ ▶ ∃ ∃ ■



ilcinstall searches for libraries and headers located in bin, lib and include relative to the directory you specify.

Example: libgsl.so is located in /usr/lib ⇒ ilcsoft.use(GSL("/usr"))

Special Cases: QT4, Java, CMake

These packages are detected automatically if they are installed in your system. Just comment them out in the config.

∃ ► Ξ = < < <</p>

On 64 bit Linux the libraries usually are located in lib64, so ilcinstall does not find them.

Trick: Create a directory with symlinks to the directories of your distribution. Name it after the version which is installed on your system and place it in the target directory and link the lib64 directory to lib:

Example:

```
ilcsoft/v01-09> mkdir -p gsl/1.12
ilcsoft/v01-09/gsl/1.12> ln -s /usr/include .
ilcsoft/v01-09/gsl/1.12> ln -s /usr/lib64 lib
ilcsoft/v01-09/gsl/1.12> ln -s /usr/bin .
```

```
Now you can use : ilcsoft.use( GSL( "1.12"))
```

Note:

The current head of the ilcinstall trunk finds the 64 bit libraries. If you check out the trunk instead of the v01-09 tag you don't have to care about 64 bit.

A = A = A = A = A = A = A



ilcinstall can be run in 3 different modes:

- ./ilcsoft-install myconfig.cfg Give a summary what is going to be installed.
- ./ilcsoft-install -p myconfig.cfg Make a "dryrun" and preview the installation.
- ./ilcsoft-install -i myconfig.cfg Perform the installation.

Run the three commands in this order. Each step will complain if anything is missing to succeed.

▲目▶ 三日 のなべ



Recent compiler versions have become more and more picky. This leads to the fact that code that compiled perfectly well on older compilers does not work any more.

A good place to look for solutions is the linearcollider forum: http://forum.linearcollider.org

In ILCSoft v01-09 the the CondDBMySQL_ILC-0-8-1 tag does not compile with gcc 4.4.1. This is solved in the current trunk, so you can change

```
ilcsoft.install( CondDBMySQL( "CondDBMySQL_ILC-0-8-1" ))
to
ilcsoft.install( CondDBMySQL( "HEAD" ))
```

If you find bugs $/\ensuremath{\,\mathrm{errors}}$ please report them to the developers, so they can be fixed!



This step is not necessary, but it's very convenient not to type the complete path all the time when calling Marlin.⁵

Example: If you are using bash put the following into your ~/.bashrc:

```
# The system variable for root
export ROOTSYS=/usr/local/root/v5.26.00b
```

For convenience: define ILCPATH and put Marlin and lcio to the path export ILCPATH=/usr/local/ilcsoft/v01-09 export PATH=\$PATH:\$ILCPATH/Marlin/v00-12/bin:\${ILCPATH}/lcio/v01-51/bin

Testing Marlin		
	Marlin -x	

 $^{^{5}}$ Instead of setting the variables manually you could also source the init_ilcsoft.sh file in your ILCSoft target directory. But this sets environment variables, PATH and LD_LIBRARY_PATH for all packages defined in the ilcinstall config. Especially for the packages from you system (QT, MySQL, cmake, gsl) this does not make sense. The few shown here are usually sufficient $\mathbb{E} \mapsto \mathbb{E} = \mathbb{E} \cap \mathbb{Q} \subset \mathbb{P}$



Additional Requirements:

Package	Comes with Distribution			Can be installed by ilcinstall			
Minuit2 ⁶		NO			NO		

- Download MarlinTPC from the repository (recommended: use the trunk) svn checkout svn://pi.physik.uni-bonn.de/MarlinTPC/trunk MarlinTPC_trunk
- Create a subdirectory named build. Change into this directory.
- Run cmake to create the Makefiles MarlinTPC_trunk/build> cmake -C \$ILCPATH/ILCSoft.cmake .. (don't forget the two dots at the end)
- Run make
- Set the MARLIN_DLL variable. You need the Minuit2 and the MarlinTPC library. Minuit2 has to be loaded before MarlinTPC. For instance in bash:

export MARLIN_DLL=\$R00TSYS/lib/libMinuit2.so:\$H0ME/MarlinTPC/build/lib/libMarlinTPC.so

For convenience you should add it to your ~/.bashrc

• Run Marlin -x to see if the library is there

⁶Usually comes with ROOT



Since r2113 the TrackFitterKalmanProcessor and TrackMakingKalmanFilterProcessor are available.

They introduce new dependencies:

Package	Comes with Distribution		Can be installed by ilcinstall			
KalTest		NO			NO	
KalDet		NO			NO	

Due to the new dependencies these processors are not build by default, so MarlinTPC still can compile without KatTest and KatDet.

To use the Kalman filters KatTest and KatDet have to be installed manually and some environment variables have to be set before compiling MarlinTPC.

Please read reconstruction/READE in your MarlinTPC directory for instructions.

EL SQC



MySQL: Download the source code from

http://dev.mysql.com/get/Downloads/MySQL-5.1/mysql-5.1.31.tar.gz/from/pick#mirrors

Minuit2

Usually Minuit2 comes with root. But there is also a stand-alone version: http://cern.ch/project-mathlibs/minuit/release/download.html

On this page you can also find installation instructions.

<=> = = = <<<>><</></></></